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REVIEW ARTICLE

The biomechanical analysis of the hand for the purpose of surgical ergonomics – A systemic review

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ABSTRACT Introduction: The hand of the human is a complicated yet sophisticated structure that is Essential for performing various functions on a daily basis. This article provided a review of the literature on the methodologies used to assess the biomechanical efficiency of the hand, including Article History anthropometry, kinematics, kinetics, and electromyography. The dimensions of the hand are Volume:6,Issue7,2024 described by anthropometry. Kinematics is the study of all hand movements and the range and type Received: 21April2024 of motion of finger joints. Tendon and joint-free analysis are covered by Kinetics. Signal-Accepted:27May2024 processing Technology is used in EMG to better understand the muscles of the hand and their doi:10.48047/AFJBS.6.7.2024.2471associating functions. Materials and Methods: For this study, articles published between 1990 and 2022 were thoroughly searched utilizing the PubMed, Elsevier Science, and Google Scholar databases. The research was limited to English-language publications that had the phrases "hand function," "hand anthropometry," "hand kinematic," "hand kinetic," "EMG of the hand," "finger joint angle," "finger tendon force," or "biomechanical hand model" in the title, abstract, or keywords. Factors like Author, Journal, Year, Scope, data, study design, identification precision, and Conclusion were taken into consideration during the analysis. Results: A total of 1765 publications were found, but 60 studies were adopted for the meta-analysis afterbeing judged to meet all selection criteria. Five methods for analyzing hand function based on a biomechanical approach were implemented in this research. These methods included anthropometry, kinematics, kinetics, and electromyography, handgrip strength. Conclusion: This study provides a review of the literature on various technologies and methodologies used for hand-function analysis, based on a biomechanical approach and the results of earlier studies relevant to hand functions. The four hand-function analysis categories listed below are covered: In that sequence, kinematics, kinetics, electromyography, and anthropometry are list. Keywords: Ergonomics 1; hand grip strength 2; biomechanical hand model 3; electromyography 4:

INTRODUCTION

The International Ergonomics Association defines ergonomics as "the scientific discipline that is concerned with the understanding of various interactions amongst humans and the other elements of a working system, and the profession that applies theory, principles, data, and methods to design a system in order to optimize human well-being and performance"¹. A significant area of ergonomics is physical ergonomics. Studying the size and form of things in relation to the anthropometry of the many people who must interact with them in order to make changes is one of the key objectives of physical ergonomic. Ergonomics hand models are used to simulate the postures used when grasping objects with distinct functions and grips. As a result, the main needa model for ergonomic is that it must support the depiction of various populations and percentiles. When grabbing the same thing for the same purposes, people with different-sized and- proportioned hands will assume various stances.²

The hand is a daily essential. It is used in all daily activities both personal and in the professional field. Musculoskeletal conditions (MSDS) like De Quervain's tenosynovitis, trigger finger, ganglionictumors, hand-arm vibration syndrome, and blackberry thumb are more common in the hand than in the lower extremities.³ When a work requires greater hand strength than the worker is able to use, repeated motion, and awkward postures can result in hand discomfort and injury.

As a result of their diminished grip strength and ability, people with hand MSDS are restricted in their activities.⁴ An essential and fundamental requirement for many movements, such as object handling, is a secure handgrip. In particular, biomechanical methodologies have traditionally been used to assess the physical capability of the hand. The four subfields of biomechanical research on the human hand are anthropometry, kinematics, kinetics, and electromyography.⁵ The Eulerian angle model and Cheng and Pearcy's model are widely applied to assess the angle, velocity, trajectory, and acceleration of a motion according to the observed markers.^{6,7,8} Anthropometry, kinematics, kinetics, and Electromyography are thefour subfields of the biomechanical study of the human hand.⁹ To examine the angle, velocity, trajectory, and acceleration of a motion according to the measured markers, the Eulerian angle modeland Cheng and Pearcy's model are frequently employed.^{10,11}

The most popular motion analysis model for describing how a rigid body is oriented in space is the Eulerian angle model. By using three rotations and Eulerian angles, every direction in Space is obtained. This makes it possible to determine the supination/pronation, abduction/adduction, and flexion/extension of the finger joint. Each model thus employs a unique set of mathematical techniques. This model is used to

compute the acceleration, velocity, and trajectory. Incontrast to Cheng and Pearcy's approach, the Eulerian angle model is capable of calculating the rotation angle.

The Eulerian angle model is the most well-liked motion analysis model that describes how a rigid body is orientated in space. By using three rotations and Eulerian angles, every direction in Space is obtained. This allows for the calculation of the fingerjoint's flexion/extension, abduction/adduction, and supination/pronation. Each model thus employs a unique set of mathematical techniques. This model is used to compute the acceleration, velocity, and trajectory. In contrast to Cheng and Pearcy's approach, the Eulerian angle model is capable of calculating the rotation angle. On the basis of 3D joint rotations, the Eulerian angle model, however, may overstate or incorrectly interpret the flexion/extension and abduction/adduction angles.¹² To understand and choose straightforward and acceptable procedures, non-experts in the field of biomechanics-such as hand-tool designers and safetysupervisors-need an in-depth understanding of the technologies and methodologies used for hand analysis.

ERGONOMICS

The Greek word Ergon meaning labor, and Nomia, meaning arrangement, comprising "ergonomics," is described by the International Ergonomics Association Council.¹³ The official description is that Ergonomics is "the science that deals with the design of things that people use in their work and everyday life and the environments in which they work and live, taking into consideration the human characteristics." To improvise security, health, welfare, and well-being, ergonomics utilizes from the human-related sciences to meet an individual's

physical, social and mentalcredentials concerning duties and atmospheres. The aim of doing this is to yield outstanding workplace productivity.¹⁴

In common language, it is the research that encloses the nurturing of the most useful relationship of function, equipment, and user.

Healthcare is well known as one of the world's one of enormous fields financially and in manpower, it provides employment to millions of individuals. It is the fastest growing industry due to rise of the ageing seniorcitizens and discovery of novel and rare healthcare challenges. The rate of increasing occupational injuries and ailments in the healthcare and wellness in the healthcare universe is greater than the usual private industry and is at an exponential rise. Even with the advent of newer technology and approaches, ergonomic issues in the healthcare industry continues to increase. Contemplating the characteristics in ergonomics-related problems is critical to developing efficient interventions. Being assertive, being quick, focused, immaculate coordination, and perfect execution of movement, surgeries require perfection.

An energetic and dynamic atmosphere is present in the Operation Theatre. A procedure is in continued progresswhen abruptly, the condition changes. Mostly, the surgeon will adapt a poor, ergonomically not favorable position so as to expose, access, and increase view of thesurgical area of interest.

Do no Harm is the main focus of the medical professionals up until lately; the soundness of the physician has been overlooked. While the patient's

wellbeing is always considered first, the healthcare and research sectors are gradually becoming astounded of and enabling support to the requirements and welfare of medical professionals. In order to minimize injuries and to ensure the wellbeing of employees, to improvise the machine interface, and to accelerate efficiency, newer technologies and products are introduced, maintaining the ergonomic standards. Due to the nature of their dailytasks, which include standing in uncomfortable positions, handling supplies and instruments, and working long hours, healthcare workers face significant ergonomic challenges and issues. The equipment's, tools, and gadgets, used in the operation theatre might not be up to the mark of the user, leading to Musculo- skeletal troubles; the scrubs might lead to allergies which might lead to anaphylactic shocks; the working hours, strain and stress of work might lead to early lifestyle ailments.

Improvising ergonomics at work place may decrease stress, strain, and fatigue amongst workers as well as aiding the surgical team of doctors to prevent musculoskeletal injuries and improvising performances. Occupational therapists work in an atmosphere where there are ergonomic dangerous factors that may result in musculoskeletal disorders (MSDs).¹⁵

Work-related musculoskeletal diseases (W.M.S. Ds) are injuries that affect the muscles, tendons, nerves, joints, and other parts of the musculoskeletal system.¹⁶ The most often affected muscle groups amongst surgeons are those present in the neck, shoulders, and lower back, with an occurrence of 20%-70%¹⁷ WMSDs in surgeons may result in various diseases, these include carpaltunnel syndrome, lumbar and cervical radiculopathy, varicose veins, and rotator cuff illnesses¹⁸ These damages have a huge impact not only on the surgeons' capability to operate, but also on proper patient care. One of the common reasons for healthcare workers to slip work is WMSD that has been demonstrated to affect proprioception, grasp force, mobility, and handling ability. As a result, the number of healthcare workers is indirectly reduced, this increases patient's waiting times, decreases patient satiety, and decreases standards of care¹⁹ feels that the increasing complexity of the dental surgical environment may have an impact on the efficiency and flow of work for dental professionals. Recent technological innovations have resulted in the invention of several advanced gadgets. Without any of them having a designated use for surgery this might lead to a surgery with an extended and dispersed operational set up, which could enhance the risk of uncomfortable circumstances and inappropriate stances while the physician is working.

The avoidance of WMSDs and increased productivity and efficiency are key components of a general improvement in the working environment for practitioners that resulted from ergonomic design suggestions for dental surgery. For the practitioner's convenience, it was advised that headrests and backrestson patient chairs should be small and easily adjusted. For the safety of the operator, patient placement shouldlean more toward supine than semi-reclined. This will lessen the need to rotate around the midsection in order o view into the mouth. The operator's recliner must accommodate the back muscles & abdominal muscles inorder to reduce tiredness. Generally, chairs have a good lumbar support and height-adjustable arm supports to make sure that the body is erect, normal posture and the feet are kept flat on the ground. The lower back supports an enduring issue. One of the more recent prototypes include to provide enough abdomen assistance and lessen lower back muscular tension, an anterior aid which is customized to the patient's chair is used. Achieving a proper posture and reducing eye strain require working in proper conditions with the correct lights and magnification. When the best direct view is going to be used, then illumination must not interfere with perception or must be radiating off the crystal surface. In order to facilitate access in the event that the angle or location of the light needs to be adjusted, the observing angle should never deviate more than 15° outfrom line of vision. Following such advice in terms of the procedure in the dental office and devices choices may boost clinician and practice comfort, efficiency, and production while improving patient comfort and ensuring that his or her requirements are met. Only a few orthodontists had previously been researched, therefore the majority of the information came from earlier studies of MSDs in dentists. Since general dentists and orthodontists do different kinds of work, their working postures must also differ from one another. To what extent the changes between both the groups are sufficient to have a clinically relevant effect is currently not known due to lack of sufficient data.²⁰

Anthropometry is the word used to describe the most comprehensive and precise method of illustrating the body's physical measures.^{21,22}

MATERIALS AND METHODS

Search Strategy: For this study, articles published between 1990 and 2022 were thoroughly searched utilizing the Google Scholar, Elsevier Science, PubMed, and Science Direct databases. The search was limited to English-language publications thathad the phrases "hand biomechanics," "hand function," "hand anthropometry," "hand kinematic," "hand kinetic," "EMG of the hand,""finger joint angle," "finger tendon force," or "biomechanical hand model" in the title, abstract, or keywords. Factors like Author, Journal, Year, Scope, data, study design, identification precision, and Conclusion were taken into consideration during the analysis. The systematic review was conducted in accordance with the PRISMA recommendations. Publications were thenanthologized, according to selection and elimination procedures, and finally screened forthe full-text article for additional clarity of the selection procedure. In this systematic review, we analyzed the articles according to the classification of various methods for the measurements of hand dimensions:

- 1. Anthropometry
- 2. Functional method (EMG, Hand gripstrength)
- 3. Kinematic method (Range of motion)

Inclusion Criteria

All the articles that were using various methodologies for hand-function. Studies analyzing the hand grip strength.

Exclusion Criteria

Literature not available in English language

Refere	Publicatio	Study	Study	(participants)	Measurers	Outcome
nces	n Year	population	design			
LailaR	2021	Bangladesh	Cross-	300 females	Finger spans,	Designing
azzaqu			sectiona		Hand grip	hand
e ²³			1		strength	instruments
						can benefit
						from using
						anthropometr
						10
						measurement
Ovidio	2020	Colombian	Observa	Alparticipants	22 hands	S of the fiand.
Rincón	2020	population	tional	41 participants	Anthronometric	measurement
-		population	tional		narameters	s were
Becerr					parameters	obtained
a ²⁴						ootamea
Amare	2020	Ethiopian		250 males	Anthropometric	Age,
Wibne		male			database of	ethnicity, and
h^{25}					Ethiopian army	cross-
						national
						comparisons
						of
						anthropometr
Derugu	2019	South Indian	Cross		Hand length hand	From hand
Vanish	2019	South mutan	Sectiona	192 subjects	breadth	length and
ri ²⁶			1 Study	17284030013	oreactin	breadth.
			1 Study			anthropometr
						ic
						measurement
						s may be
						utilizedto
						determine
		5100	01			stature.
ArgiSo	2018	Different	Observa	259	Hand length and	Established
n1-'		Nationalities	tional	university	stature	anthropometr
		Malaysia, Chi	students			for
		nese,muta				101 determining
						the height of
						Malaysia's
						three main
						races.
Nuriye	2018	Turkey	Cross-	141 students	Hand length and	Males are
Kübra			sectiona		width	longer and
Bayrak			1			wider than
tar ²⁰						remales.

Table 1: Anthropometric method and biomechanical hand model in previous studies

Ravnee tSandh u ²⁹	2017	Amritsar, Punjab, India	Cross- sectiona l study	100 young healthy men and females	Height, weight, body mass index (BMI), hand length, hand width, and hand grip strength	Males have stronger grips than females.
Archan aChaha 1 ³⁰	2014	Allahabad ,India	Observa tional	37district junior male basketball players	Height, weight, hand width, hand length and hand span,	Except for the hand length, which was not significantly different, the left hand's hand breadth and hand spread were both larger.
Umam a NisarS hah ³¹	2012	Karnataka	Cross- sectiona l study	50 healthy female subjects	Anthropometric measures of the hands and forearms, as well as height, weight, and body mass index (BMI).Grip strength in both the dominant and non-dominant hands	The findings demonstrate positive correlation between hand grip strength and height, weight, hand length, hand spread, wrist Circumferenc e, and fore arm girth. In healthy Indian females, hand grip strength does not correlate with BMI or hand width.
Arunes hChan dra ³²	2011	Haryana	Observa tion	878	Internal grip diameter, grip span, hand length and hand circumference.	All values between the hand length and hand circumferenc e are substantial and positively associated.

Table 2: Functional (EMG) method and biomechanical hand model in previous studies

References	Year	Study	Study	(Participants)	Measurers	Outcome
		population	design			
Néstor	2021	Spain	Cross	42 subjects	EMG of	To enhance rehabilitation
J.Jarque-			sectional		hand and	procedures, control of
Bou ³³					forearm	prosthetic devices, a better
					muscles	knowledge of human hand
						behavior, and more
						accuratebiomechanical
						models, the most significant
						problems and unresolved
						Concerns are listed.
M.A.	2019	Mexico	Observation	50 subjects	EMG Signals,	The findings were
Aceves-					EMG	contrasted with those from
Fernandez ³⁴	-				Classification	conventionalmachine
						learning techniques, and the
						benefits of using the
						suggested methodology over
						them are emphasized.

Cable 3: Functional (Hand grip strength) and biomechanical hand model in previous	ious
tudies	

References'	Year	Study	Study design	(participants)	Measurers	Outcome
		population				
Razzaque L. ³⁵	2021	Bangladesh	Observational and cross sectional	300 females	Five finger spans andhand grip strength were tested.	Age-related differences in grip strength were clearly seen in both hands. Age- related variations in finger spans were non- significant. The identical
						hand's fingerlengths and grip tensile strength were positively correlated.
Shaheen M. ³⁶	2021	Saudi Arabia	Cross- sectional study	139 healthy females college students	Hand Grip Strengthand Pinch strength	When evaluating hand function throughout the rehabilitation process, normative values can be utilized as a therapeutic guide while taking the population's age and palmar breadth into Consideration.
Sandhu R. ³⁷	2017	Punjab	Cross- sectional study	100 male andfemale	Using a Jamar dynamometer, handgrip strength was evaluated.	Males tend to have strongergrips than females.
Rawat S. ³⁸	2016	India	Cross- sectional study	375 healthy Indian females	Weight, forearm length, arm length, hand	Grip strength may be predicted in Indian office- going females using anthropometric measures

		width, hand	and body
		gripstrength,	Composition factors.
		and	Hand grip strength is
		body mass	closelyrelated to These
		index(BMI)	variables.

Table 4: Kinematic method and biomechanical hand model in previous studies

References'	Year	Study	Study	(participants)	Measurers	Outcome
		population	design			
Néstor	2020	Spain	Cohort	22	Digit arching	It may be
J.Jarque-			study	health	(flexion of the	advantageousto
Bou ³⁹				ysubjects	proximal	choose activities
					interphalangeal	for
					joints), palmar-	rehabilitation and
					thumbcoordination	handfunction
					(coordination of the	evaluations if
					palmar and	groups of tasks with
					carpometacarpal	comparable kinematic
					flexions of the	needsin terms of
					thumb),thumb	synergy arefound.
					opposition, and	
					thumb arch are all	
					instances of flexion	
					and abduction of the	
					meta	
					carpophalangeal	
					finger joints.	
Jumana	2018	Germany	Cross	100	MCP	A fundamental linear
Ma'touq ⁴⁰			Sectional	participants	flexion/extension,	correlation between
			Study		and	surfaceand skeleton
					abduction/adduction,	Rotational angles was
					proximal	discovered after we
					interphalangeal, and	were able to enhance
					distal	literature.
					interphalangeal	
Henk G	2014	Netherlands	Cross	100	Inertial sensors used	Inertial and magnetic
Kortier ⁴¹			Sectional	subjects	in an ambulatory	sensorsare significant
			Study		system that is	for ambulatory
					maybe linked to the	examination of the
					hand, fingers, and	human hand and
					thumb. It allows for	finger kinematics,
					the precise	according to this
					positioning of the	study's findings
					hand as well as the	regarding static
					full 3D	accuracy, dynamic
					reconstruction of all	range, and
					finger and thumb	repeatability. It makes
					joints. Experimental	it possible to estimate
					evaluations were	joint movements with

		done to determine	a number of degrees of
		the static accuracy,	freedom using
		dynamic range, and	inexpensive sensors.
		repeatability of the	-
		system.	

References'	Year	Study	Study	(participants)	Measurers	Outcome
		population	design			
Onathan	2006	South	Cross	20	Height, Gender	These findings can aid
		Korea	Sectional	participants	Angle, Direction	in theassessment of
L.Morse ⁴²			Study		Velocity,	cumulative trauma
					Direction Angle,	syndromes, but further
					right hand and	study on the dynamic
					arm injuries.	measurements of the
						hand and wrist complex
						and the creation of
						dynamic force measuring
						standards are required.

ABBREVIATIONS

(EMG) -Electromyography(ROM)- Range of motion

(MSD)- Musculoskeletal disorder (sEMG)- surface electromyography (RMS)-Root mean square

(MPF)-Mean power frequency

(MVC)-Maximal voluntary contraction

DISCUSSION

The science of anthropometry includes methods for analyzing the data from manual measurements. Technology is used in kinematics to assess the ROM of each hand joint, including those in the fingers and wrist. Kinetics is the study of technology and a variety of kinetic hand models for analyzing joint and tendonforces. EMG provides information on the muscles of the hand and the functions associated with it, Signal processing technology, and SEMG technology.

According to the study's objectives, anatomical measuring variables are often categorized for use in general or application surveys. A general survey's primary goal is to describe a population, and it does this by measuring a wide range of people's hands. In contrast, an application survey simply selects and measures the factors that are closely relevant to the product under consideration. It also examines fewer and more precise dimensions. As a result, depending on the goal, different dimensions and populations are measured. However, insufficient research was done to determine the ideal person count and related parameters.⁴³ Therefore, to establish the ideal sample size for obtaining accurate statistical information, a thorough assessment of hand Anthropometry is necessary. Kinetics research has examined the force, moment, and torque in tendons and fingers. Both direct and indirect measurements of these variables arepossible. The instruments employed include force gloves, pinch gauges, dynamometers, new force transducers, and tendon force measuring devices. Hand functions are coordinated by intrinsic and extrinsic muscle groups. In a hand-function study utilizing SEMG,⁴⁴ six extrinsic muscles are typically examined. Hence, using electromyography during contractions that change throughout time necessitates many interpretations than doing so during

static ones. So, it is obvious that the biomechanical approach of the hand is a multidisciplinary study of the mechanical force and movement of the musculoskeletal system of the hand. With the use of biomechanical research, hand instruments may be designed more expertly and effectively.

The estimation of human physical characteristics is called anthropometry. The mean of the human population has changed in terms of physical size with the evolving time. People these days are often heavier and taller than in prior generations. According to the science relating anthropometrics, population dimensions are evaluated based on population size, strength, and other characteristic features.

These measures are used to garner a collection of information with regards to in terms of shape and size, corresponding to the proportion of population under study⁴⁵ Individual physical qualities interact with extrinsic elements in the environment when carrying out any specific job activity in order to affect the development of musculoskeletal complications. The next section will assess quickly what is known about how women and men differ with regards to anthropometry as this specific work focuses on how sex variations in anthropometry intermingle with extrinsic job variables to impact the gradual development of work- related musculoskeletal complications and illnesses.

Designing hand-guarded, hand-controlled, and hand-operated instruments is possible with the use of hand anthropometry data. It is convenient to measure hands using a variety of instruments and gadgets. These days, 3D scans are the method of choice since they can simply and precisely assess a variety of hand regions. In a static condition, the measurements of the hand are mostly measured under the crease of length, width, and circumference.⁴⁶

A large number of researches have been done to assess the, trajectory, acceleration, angle, & velocity of various hand related functions. Various instruments are often used to gauge different functions of hand like goniometers, electro-goniometry, x-rays, MRI, & motion analysis by markers based. Commontechniques for clinical observation include X-ray and MRI examinations. However, radiationexposure is a possibility with X-ray measurements.⁴⁷ It is challenging to use goniometry to assess the thumb trapeziometacarpal joint.⁴⁸ In a bid to compensate for such limitations, recent research is aggressively examining the application of motion detection methods for evaluating hand capabilities. Although they continuously analyze both movement & posture by calculating three - dimensional motion analysis.

A 3D motion analysis system is often used ina variety of disciplines for the accurate evaluation of kinematic parameters. In comparison to previous techniques, this technique is more reliable in obtaining 3D data.⁴⁹ Three-dimensional motion evaluation is required to analyzed the kinematic parameters for the kinematic hand model and marker attachment approaches. Even though any marker attachment method is appropriate here, the "one marker per joint" method is advised for increased patient comfort and simple marker insertion in static settings. Due to their robustness to skin movement, the "three markers per segment" and "cluster marker" approaches are advised for studies carried out in dynamic environments since they evaluate hand motions more precisely.⁵⁰ the hand's most significant and developed component, with the widest Range of functions⁵¹ Therefore, future studies will look at the thumb's ROM and functionalities, which will be assessed in three dimensional.

In general, direct and indirect measurements may be used to categorize the technologies for kinetics evaluation. The outside load is normally evaluated, whereas the interior weight is frequently predicted analytically utilizing kinetic models.⁵¹ Measure the force, moment, of functions of the hand, has been the focus of several earlier investigations. Appropriate anthropometry information, like segment mass, and center of gravity, is needed to evaluate these in a joint. For the formation of hand kinetics models in future studies, precise anthropometry data of the hand is also required.⁵³

With the increasing prevalence of laparoscopic procedures, practitioners are reporting fatigue

and discomfort of varied varieties. The most common discomforts reported are located in the arms, neck, and upper back.

In order to study the mechanisms of the muscular fatigue, EMG is one of the best methods. This is because EMG measures and evaluates the Action Potential and Resting Membrane potential of muscles. The quantification of physical workload and muscular discomfort by EMG is a known method and frequently used by ergonomists. An efficient way to assess a variety of biomechanical traits, such as muscular action, exhaustion, and propagation pace, is through Surface EMG (sEMG) analysis.⁵⁴ The firing rate in sarcolemma is the action potential in a musculoskeletal system and is dependent on strength of stimulus. An assessment of usage of muscle and the muscular loading magnitude along with its relation to muscular effort is provided by EMG.⁵⁵ Evaluation of muscle activation throughout various professional tasks is common.⁵⁶ Christensen defined muscular exhaustion as a decrease in a muscle's ability to generate force. Both intrinsic and extrinsic groups of muscles of hand region are accountable for various aspects of hand physical functioning. Contrary to intrinsicmuscles, that is entirely found in the hand and is responsible for the digit motions, and the extrinsic compartment of the muscles are noticeably significantly larger.

The extrinsic muscles are further divided into the anterior and posterior groups where each can further be classified as superficial or deep muscle. The anterior muscles perform the function of flexion and extension is the action of the posterior muscles. The most crucial EMG procedures are selecting the appropriate muscles, correctly attaching the electrodes, and selecting an appropriate signal-processing technique for the intended research. The hand muscles thatare most frequently utilized to test the hand's efficiency using EMG, the majority of investigations have employed signal-processing techniques like RMS and MPF. Dynamic hand functions have not been considered in prior research on muscle exhaustion and features according to the Electromyography signals. They just took into account the MVC's relative muscular activity. Dynamic hand movements, on the other hand, include the depth and length of the muscle fibers, which fluctuate over time and space. As a result, alterations take place between the muscle fiber and the SEMG electrode. Moreover, as the muscular contraction velocity changes, a muscle- tendon moment differential is produced.⁵⁷Because of this, the electromyography signal for dynamic hand activities must be interpreted in different ways than for static hand functions.

Hand grip strength has been noted as an important factor in predicting impairment in musculoskeletal complications, risk of falling, cracks in osteoporosis, and thickness of bone minerals. Three studies that looked at how hand dominance affects grip strength found that the dominant hand had statistically significant grip strength advantages over the non-dominant hand.⁵⁸

A sturdy wrist is necessary for power gripping. According to biomechanics, a stable wrist prevents the forces generated bythe tendons as they travel across the carpus from dissipating. One of the most intricate biomechanical systems is the human hand. A succession of longitudinal and transverse arches is formed by a system of bony segments.⁵⁹ In essence, there are two transverse arches: the distal transverse arch, which is produced by the metacarpal heads of the fingers, and the proximal transverse arch, which is formed by the carpal bones. The five digital rays' bones make up the longitudinal arches. The carpal bones are thepoint at which the proximal transverse and longitudinal arches converge. Therefore, the longitudinal arches and other key structures for hand function both benefit from the stabilizing effects of the carpal bones. Because the arch biomechanically resists more force than other structures, arches are commonly used in both ancient and contemporary engineering and architecture. Carpal bones are a component of the joint motion arc and aid in stabilizing hand motion. The lengths of the metacarpal, proximal phalanx, middle phalanx, and distal phalanx bones all fall within the Fibonacci ratio of 1:1.618034, which is wellknown. According to observations made byother

researchers⁶⁰ the ratio is better suited by these bones' functional lengths calculatedusing the joints' centers of rotation than by their absolute lengths. In addition to the Parthenon in Greece, this ratio can also be found in the nautilus shell, sunflowers, eggshells, spiral galaxies in space, and sunflowers. The surgeon's job is to minimize this functional loss by restoring the anatomy where it is feasible and tricking Mother Nature when necessary. This geometric design, in this ratio, and the bonystructures of the hand produce an equiangular spiral of joint motion arcs. The hand may be described as consisting of a stable wrist and a minimum of two digits that can exert some force on one another. Forgrasping to be possible, it is ideal for one or both of the digits to be mobile. One digit canbe stable and have mobility in its simplest form so that it can move against the stable post. Digits gain from feeling things and from not hurting, which makes it easier for them to be used. The majority of hand functions are made up of seven biomechanical hand movements.

CONCLUSION

Simply said, Hand anthropometry serves as the foundation for biomechanical analysis. The most typical measuring variable is the range of motion (ROM). Designing hand devices and hand rehabilitation often involves using ROM and anatomical measurements. The (3D) motion evaluation model is now the most used technique for evaluating kinematic variables such as trajectory, angle, velocity, and acceleration. For analysis and comparison, this system requires pre-set markers and kinematic models. Based on the requirements of various researches, a variety of sets and models have been created, and the system's accuracy has increased significantly over time. As a result, the data gathered by this system helps to broaden researchers'understanding, enabling them to select an appropriate method for development and improvement. The most frequent applications of EMG in research are to measure muscular activity, exhaustion, and conduction velocity. Effective assessment requires an understanding of signal processing methods, electrode placement, muscle location, and the operation of the EMG instrument. In clinical settings, handgrip strength is a key factor in physical stability and overall health. In older people, it also helps predict general morbidity, complications following surgery, and surgical outcomes. The prevention of MSDS is crucial for enhancing working conditions and performance, which calls for the application of certain biomechanical concepts. In reality, the hand is primarily assessed to minimize the risk of musculoskeletal disorders. This study provides a review of the Literature on a few technologies and approaches for analyzing hand functions that are using a biomechanical methodology and thefindings of prior research on hand functions. Analyses of the four hand-function categories-anthropometry, kinematics, kinetics, and electromyography are included.

With the advancement in medical science, different technologies are being incorporated to improve the efficiency of medical professionals. Various new instruments havebeen developed to save the human life. But the only dilemma is that they are designed according to the anthropometric parameters of kinematic hand model developed by European countries.

It is an established fact, that Indian parameters differ widely from other countriesdue to its genetic and geographical pattern.

Besides this, lot of literature is available regarding the anthropometric parameters of Indian hand in both the sexes. But, for the development of kinematic hand model, otherparameters like finger joint angles, finger tendon force, range of movements, muscle strength etc. are also required. So, our study will provide these parameters to develop Indian hand kinematic model.

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